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COMPUTING SOLUTIONS OF THE REDUCED WAVE EQUATION.(U)
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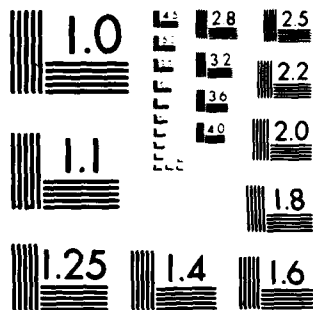
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FINAL REPORT

AIR FORCE GRANT NO. F-49620-79-C-0193

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The final report for Air Force Grant No. F-49620-79-C-0193 consists of the annual progress reports dated November 21, 1979 and August 25, 1980, as well as the following report for 1980-81:

During 1980-81 various numerical experiments were made on one-dimensional model inverse problems modelled by a method that is extendable to higher dimensions. The underlying problem is to recover the speed of propagation or the shape of an object from a scattered field.

The one dimensional problem that was investigated was based on the wave equation with potential

$$u_{tt} - u_{xx} + q(x)u = 0$$

where the function to be recovered is the potential $q(x)$. The model initial conditions were $u = 0$, $u_t = -2\delta'(x)$. The model boundary condition was $u = 0$ on $x = 0$. And the "extra" condition which determines $q(x)$ is either (a) $\partial u / \partial x$ on $x = 0$ for all time or (b) the scattered field $u \sim \delta(t-x) + R(t-x)$ at $x = +\infty$. The free space ($q=0$) solution is $u = \delta(x-t) - \delta(x+t)$. The distorted plane wave $P(x,t)$ is defined by the condition that it is a solution of the equation and at $x = -\infty$, $t \rightarrow +\infty$,

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it becomes $\delta(t-x)$ (exactly if q has compact support)
and P is written as $\delta(t-x) + P_{\text{scat}}$.

The linearized equation based on the assumption
that $q \ll 1$ and that terms of order q^2 may be
neglected, yields for (a)

$$q = + 2 \frac{d}{dx} \left[\mathcal{H}(2x) - P_{\text{scat}}(0, -2x) \right]$$

with $\int_{-\infty}^t \frac{\partial u}{\partial x} dt \Big|_{x=0_{\infty}} = \mathcal{H}(t) \text{ for } t > 0 ;$

$$q = -2 \frac{d}{dx} R(2x)$$

for (b).

The numerical method is based on the well-known
formula that follows from the propagation of singularities

$$q = 2 \frac{d}{dx} \lim_{t \rightarrow x+} u(x, x)$$

and then representing $u(x, x)$ by means of distorted
plane waves. (All these have analogous formulas in
higher dimensions.)

The analogues of the above equation are for (b)

$$q = -2 \frac{d}{dx} R(2x) + \frac{d}{dx} \int_0^{\infty} (P_{\text{scat}}(x, x-s) - P_{\text{scat}}(-x, x-s)) R(s) ds$$

and for (a) we insert in this formula



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$$R(s) = -\mathcal{H}(s) + P_{\text{scat}}(0, -s) + \mathcal{H}(0) \int_{-\infty}^s P_{\text{scat}}(0, -s') ds' \\ + \int_0^{\infty} \mathcal{H}(t) P_{\text{scat}}(0, t-s) dt$$

The idea is to use one of these formulas as part of an iteration. We guess q and P and recompute q using the above formulas for cases (a) or (b).

Note that if the given data vanishes in case (b) we recover $q \equiv 0$ but in case (a) we donot.

We have been unable to implement (a) as planned. The reason is that we must operate in a finite region and use a radiation condition at a finite distance. In our case for example with q a simple quadratic with support in $|x| < 2$, over $-8 \leq x \leq 8$ and $0 \leq t \leq \dots$. The errors produced are compounded in case (a). The potential could only be recovered to 40% of its original value with an error of about 5% of the maximum potential. However, the potentials were well beyond the range of the linear theory.

In case (b) even with a coarse mesh the results are surprisingly worse.

The results are being written up as a technical report to be issued at the Courant Institute.

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